

# Catalina Series

## Full-featured Benchtop Dispense System

- Automatic Vision
- Automatic Nozzle Calibration
- Laser Sensing & Profiling



Our Catalina benchtop system is a full-featured platform. These are just some of the standard features: automatic vision, laser surface sensing, and nozzle alignment.

Our tabletop dispensing robot provides you with **accurate and repeatable** dispense results. Any model in the Catalina Series can be configured with an optional, **heated work area**.

- Easy to learn, computer-based software with Windows operating system.
- Easy point-based teaching for all axis movement. Able to set point jobs and various parameters.
- Automatic alignment and positioning with high resolution camera.
- Create dispense paths using camera teach or on-screen graphic editing.
- Import DXF files for complex path programming.
- I/O ports provide the flexibility to add advanced features/equipment.

### Models

#### **Catalina L**

High repeatability with contact probe or non-contact laser surface sensing.

#### **Catalina TR**

Dispense with **Tilt and Rotate** function.



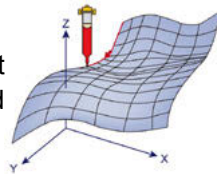
#### **Catalina Mini**

For dispensing on small substrates. Work area: 200 mm x 200 mm (7.9" x 7.9")

### Standard Features

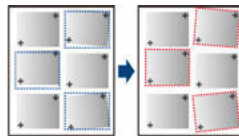
#### *Automatic Vision*

System automatically locates alignment points to account for product shift and rotation.



#### *3D Dispensing*

Laser traces the dispense path and measures surface variation, then adapts height of the dispense tip to maintain a consistent gap.



#### *Image Alignment*

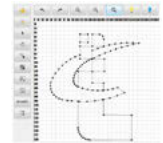
Vision system locates alignment points to account for product rotation.

#### *Automatic XYZ Nozzle Calibration*

Locates dispense tip in X, Y, Z for accurate fluid placement.

#### *Graphic Edit & DXF Support*

User-friendly graphic editing to create a dispense path. AutoCAD DXF files are supported.



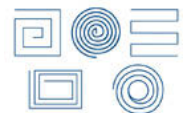
#### *Matrix Dot Dispensing*

Easily duplicate a common pattern in a matrix.



#### *Fill Area*

Multiple types of fill area and dispense patterns. Easy to teach.



#### *Laser*

Non-contact surface sensing.



# Catalina - Benchtop Dispensing

## Add-On Options

Common Options*	Description
FPC	Real time process control for pump(s).
Heated Work Table	For heating substrates up to 120° C (248° F).
Fluid Level Detect	Notifies operator when fluid level attains set point.
Contact Surface Sensor	Alternative to laser surface sensor.
Laptop Computer	Runs the software.
Teaching Pendant	Remotely controls tabletop robot.

\* Contact GPD Global about additional options and features.

## Pump Compatibility

Application	Pumps / Accessories
High viscosity pastes, glues, adhesives.	Precision Auger Pump
High speed, low viscosity.	Jetting Pump (NCM5000)
No drip, volumetric repeatability.	Volumetric Pump (PCD)
Simple liquid dispense applications, low-to-mid viscosity.	Time Pressure
Real time process control.	Fluid Pressure Control (FPC) for use with Precision Auger & Jetting (NCM5000) pumps, as well as Time Pressure Dispensing

## Specifications

Specification	Catalina L	Catalina TR	Catalina Mini
Dispense Pump Capacity	Single		
Height Sensing	Contact or non-Contact (Laser)	Non-Contact (Laser)	—
Range of Operation	X, Y, Z Axes	400 x 400 x 150 mm	200 x 200 x 50 mm
	R-Axis (rotation)	—	±360°
Payload	X-Axis (workpiece)	14 kg (30.9 lbs)	7 kg (15.4 lbs)
	Y-Axis (pump)	5 kg (11.0 lbs)	3.5 kg (7.7 lbs)
Speed, maximum Point to Point	X & Y Axes	800 mm/sec (31.5"/sec)	700 mm/sec (27.56"/sec)
	Z Axis	400 mm/sec (15.75"/sec)	250 mm/sec (9.84"/sec)
	R-Axis (rotation)	—	900°/sec
Speed, maximum Continuous Path	X, Y, Z combined	850 mm/sec (33.46"/sec)	600 mm/sec (23.62"/sec)
Resolution	X, Y, Z Axes	0.001 mm	
	R-Axis (rotation)	—	±0.01°
Repeatability	X & Y Axes	±0.007 mm	±0.006 mm
	Z Axis	±0.007 mm	±0.01 mm
	R-Axis (rotation)	—	0.008°
Interpolation Function	3D linear and arc		
Data Storage	On-board and backed up via PC Software when connected and downloaded		
Dimensions (W x D x H) (excludes protrusions)	651 x 668 x 715 mm (25.6" x 26.3" x 28.1")	651 x 668 x 844 mm (25.6" x 26.3" x 33.2")	323 x 387 x 554 mm (12.7" x 15.2" x 21.4")
Weight - Robot (approximate)	51 kg (112.4 lbs)	55 kg (121.3 lbs)	20 kg (44.1 lbs)
Simple PLC Function	Up to 100 programs with up to 1,000 steps/1 program		
Program Capacity	999 programs		
User Input/Output	16 Inputs / 16 Outputs (I/O-Sys Port)		
	8 Inputs / 8 Outputs, includes 4 relay outputs (I/O-1 Port)		
	RS232C		
	USB memory connector		
	PoE Industrial Hub connection		
Drive Method	5 phase pulse/stepping motor		
Programming Method and Teaching	Easy point-based teaching for all axis movement. Able to set point jobs and various parameters. Remote Teaching (JOG) / Manual Data Input (MDI) PC Teach / Graphic Edit		
Power	110-220 Volts AC		
Air Pressure	5.86-6.89 bar (85-100 psi)		
Work Temperature	0-40° C (32-104° F)		
Working Relative Humidity	35-85% no condensation		
Automatic Vision	Standard		—